

## DRAFT AGENDA

Time	Description
8:45 am	<b>Registration and Networking</b>
9:15	<b>Welcome</b> – ITS Canada Janneke van der Zee
9:20	<b>Welcome</b> – OTC Geoff Wilkinson
9:25	<b>Agenda Overview</b> – Ross McKenzie, uWaterloo/ WatCAR
9:30	<b>ITS in Smart Cities Part 1 – Panel Presentations</b> <b>Chair:</b> Kurtis McBride, Co-Founder & CEO Miovision <ul style="list-style-type: none"> <li>• Region of Waterloo or University of Waterloo (tbd)</li> <li>• Jeff Smart, TACEL – Industry Supplier perspective</li> <li>• Chris Philp, CIMA+</li> </ul>
10:30	<b>Health Break &amp; Networking</b>
10:45	<b>ITS in Smart Cities Part 2 – Panel Discussion</b> Are we ready? Role of Big Data (Gov't of Canada) <b>Chair:</b> Jessie Coleman – City of Toronto, Big Data Innovation Team <ul style="list-style-type: none"> <li>• Region of Waterloo (tbd)</li> <li>• Jeff Smart, TACEL</li> <li>• Chris Philp, CIMA+</li> </ul>
11:45	<b>Lunch &amp; Networking</b>
12:30 pm	<b>Keynote: Public Transit and ITS</b> Dr. Brendon Hemily Independent Consultant, Public Transportation Industry
1:15	<b>Autonomous Vehicles</b> Ross McKenzie, WatCAR <ul style="list-style-type: none"> <li>• AVs 1–2–3, Challenges, Market Overview</li> </ul>
2:00	<b>Connected and Autonomous Vehicle (CAV) Technologies</b> <b>Chair:</b> Fahad Shuja – Ontario Good Roads Association <ul style="list-style-type: none"> <li>• Mara Bullock, WSP – GTHA CAV Readiness Plan</li> <li>• Ryan Lanyon, City of Toronto – AV Policy Initiative</li> <li>• Colin Dhillon, APMA –Stratford CAV Demonstration Zone [AVIN/ APMatec]</li> </ul>
3:00	<b>Summary &amp; Closing Remarks</b>
3:30	<b>uWaterloo/ WatCAR Tours</b> -participants can select 1 or 2 tours (30 minutes/ tour) <ol style="list-style-type: none"> <li>1. <a href="#">RoboHub/ IDEAs Clinic/ Student Design Centre</a> (E7, E5)</li> <li>2. <a href="#">Multi-Scale Additive Manufacturing [MSAM] Laboratory</a> – 3D Printing (E7, EC4)</li> <li>3. <a href="#">Green and Intelligent Automotive [GAIA] Facility</a> – Advanced Powertrain (E3)</li> </ol>